

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	6395	((356/28.5,27,28,4.09-4.1) or (701/93-98,116-119,301,302,28)). CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/01/16 13:03
L2	0	L1 and relatave postion and relatave velocity and motion attibute discriminat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L3	0	L1 and relatave postion and relatave velocity and motion attibute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L4	0	L1 and relatave postion and relatave velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L5	1	L1 and relative position and relative velocity and motion attribute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L6	2363	Takahama.inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L7	45	L6 and relative position	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L8	5	L7 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03

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L9	9	L6 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L10	126	L6 and (laser radar or laser or radar)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L11	28	L10 and vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L12	171	L1 and relative position and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L13	144	L12 and (radar or laser)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L14	0	L12 and relative position same calculat\$3 near4 multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L15	0	L12 and relative position same calculat\$3 same multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L16	53	L12 and relative position same calculat\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03

EAST Search History

L17	0	L12 and calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L18	186	calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L19	32	calculat\$3 near3 multiple near7 accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L20	37	L13 and stationary object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L21	42	L13 and (immobile or still or stationary or motionless) object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L22	19	L13 and (immobile or still or stationary or motionless) object same vehicle same relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L23	0	L13 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat@4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L24	9	L13 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03

EAST Search History

L25	9322	((701/93,96,301,302) or (340/425.5, 435,436,438,901,903) or (342/61, 70)).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/01/16 13:03
L26	0	L25 and relative velocity and relative position and motion attribute discriminating	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L27	6395	((356/28.5,27,28,4.09-4.1) or (701/93-98,116-119,301,302,28)).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/01/16 13:03
L28	171	L27 and relative position and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L29	144	L28 and (radar or laser)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L30	19	L29 and (immobile or still or stationary or motionless) object same vehicle same relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L31	0	L28 and relative position same calculat\$3 same multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L32	0	L28 and relative position same calculat\$3 near4 multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03

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L33	0	L27 and relative position and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L34	0	L28 and calculate 3 near 3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L35	2363	Takahama.inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L36	0	L27 and relative position and relative velocity and motion attribute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L37	45	L35 and relative position	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L38	5	L37 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L39	9	L35 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L40	0	L27 and relative position and relative velocity and motion attribute discriminant 4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03

EAST Search History

L41	186	calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L42	9322	((701/93,96,301,302) or (340/425.5, 435,436,438,901,903) or (342/61, 70)).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/01/16 13:03
L43	0	L42 and relative velocity and relative position and motion attribute discriminating	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L44	126	L35 and (laser radar or laser or radar)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L45	1	L27 and relative position and relative velocity and motion attribute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L46	9	L29 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L47	37	L29 and stationary object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L48	32	calculat\$3 near3 multiple near7 accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03

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L49	53	L28 and relative position same calculat\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L50	28	L44 and vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L51	0	L29 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat@4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L52	42	L29 and (immobile or still or stationary or motionless) object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L53	6395	((356/28.5,27,28,4.09-4.1) or (701/93-98,116-119,301,302,28)). CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/01/16 13:03
L54	0	L53 and relitave postion and relitave velocity and motion attribute discriminat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L55	0	L53 and relitave postion and relitave velocity and motion attribute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L56	0	L53 and relitave postion and relitave velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03

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L57	2363	Takahama.inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L58	126	L57 and (laser radar or laser or radar)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L59	171	L53 and relative position and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L60	0	L59 and relative position same calculat\$3 near4 multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L61	0	L59 and relative position same calculat\$3 same multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L62	0	L59 and calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L63	186	calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L64	144	L59 and (radar or laser)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03

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L65	42	L64 and (immobile or still or stationary or motionless) object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L66	0	L64 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat@4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L67	9322	((701/93,96,301,302) or (340/425.5, 435,436,438,901,903) or (342/61, 70)).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/01/16 13:03
L68	0	L67 and relative velocity and relative position and motion attribute discriminating	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L69	6395	((356/28.5,27,28,4.09-4.1) or (701/93-98,116-119,301,302,28)).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/01/16 13:03
L70	171	L69 and relative position and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L71	144	L70 and (radar or laser)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L72	19	L71 and (immobile or still or stationary or motionless) object same vehicle same relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03

EAST Search History

L73	0	L70 and relative position same calculat\$3 near4 multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L74	19	L64 and (immobile or still or stationary or motionless) object same vehicle same relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L75	0	L70 and relative position same calculat\$3 same multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L76	0	L70 and calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L77	0	L69 and relitave postion and relitave velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L78	2363	Takahama.inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L79	186	calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L80	9322	((701/93,96,301,302) or (340/425.5, 435,436,438,901,903) or (342/61, 70)).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/01/16 13:03

EAST Search History

L81	0	L69 and relitave postion and relitave velocity and motion attibute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L82	0	L69 and relitave postion and relitave velocity and motion attibute discriminat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L83	42	L71 and (immobile or still or stationary or motionless) object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L84	1	L53 and relative position and relative velocity and motion attribute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L85	1	L69 and relative position and relative velocity and motion attribute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L86	0	L80 and relative velocity and relative position and motion attribute discriminating	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L87	126	L78 and (laser radar or laser or radar)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L88	0	L71 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat@4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03

EAST Search History

L89	45	L57 and relative position	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L90	28	L58 and vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L91	5	L89 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L92	53	L59 and relative position same calculat\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L93	9	L57 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L94	32	calculat\$3 near3 multiple near7 accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L95	37	L64 and stationary object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L96	9	L64 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03

EAST Search History

L97	45	L78 and relative position	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L98	28	L87 and vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L99	9	L78 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L100	9	L71 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L101	37	L71 and stationary object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L102	5	L97 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L103	53	L70 and relative position same calculat\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03
L104	32	calculat\$3 near3 multiple near7 accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2007/01/16 13:03

EAST Search History

S1	5934	((356/28.5,27,28,4.09-4.1) or (701/93-98,116-119,301,302,28)). CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/03/15 11:44
S2	0	S1 and relative position and relative velocity and motion attribute discriminat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 14:03
S3	0	S1 and relative position and relative velocity and motion attribute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 14:03
S4	0	S1 and relative position and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 14:04
S5	1	S1 and relative position and relative velocity and motion attribute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 14:31
S6	2242	Takahama.inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 14:04
S7	41	S6 and relative position	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 14:06
S8	4	S7 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 14:08

EAST Search History

S9	8	S6 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 14:14
S10	120	S6 and (laser radar or laser or radar)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 14:15
S11	25	S10 and vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 14:15
S12	151	S1 and relative position and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 14:31
S13	126	S12 and (radar or laser)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 16:21
S14	0	S12 and relative position same calculat\$3 near4 multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 16:10
S15	0	S12 and relative position same calculat\$3 same multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 16:10
S16	46	S12 and relative position same calculat\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 16:13

EAST Search History

S17	0	S12 and calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 16:13
S18	159	calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 16:13
S19	26	calculat\$3 near3 multiple near7 accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 16:13
S20	35	S13 and stationary object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 16:31
S21	40	S13 and (immobile or still or stationary or motionless) object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 16:32
S22	18	S13 and (immobile or still or stationary or motionless) object same vehicle same relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 16:33
S23	0	S13 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat@4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 16:33
S24	9	S13 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/09 16:35

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S25	8493	((701/93,96,301,302) or (340/425.5, 435,436,438,901,903) or (342/61, 70)).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/03/15 11:45
S26	0	S25 and relative velocity and relative position and motion attribute discriminating	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/03/15 11:46
S27	6193	((356/28.5,27,28,4.09-4.1) or (701/93-98,116-119,301,302,28)).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/09/13 11:32
S28	0	S27 and relitave postion and relitave velocity and motion attribute discriminat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S29	0	S27 and relitave postion and relitave velocity and motion attribute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S30	0	S27 and relitave postion and relitave velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S31	1	S27 and relative position and relative velocity and motion attribute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S32	2320	Takahama.inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32

EAST Search History

S33	43	S32 and relative position	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S34	4	S33 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S35	8	S32 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S36	125	S32 and (laser radar or laser or radar)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S37	27	S36 and vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S38	162	S27 and relative position and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S39	136	S38 and (radar or laser)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S40	0	S38 and relative position same calculat\$3 near4 multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32

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S41	0	S38 and relative position same calculat\$3 same multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S42	50	S38 and relative position same calculat\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S43	0	S38 and calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S44	176	calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S45	28	calculat\$3 near3 multiple near7 accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S46	36	S39 and stationary object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S47	41	S39 and (immobile or still or stationary or motionless) object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S48	19	S39 and (immobile or still or stationary or motionless) object same vehicle same relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32

EAST Search History

S49	0	S39 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat@4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S50	9	S39 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S51	8966	((701/93,96,301,302) or (340/425.5, 435,436,438,901,903) or (342/61, 70)).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/09/13 11:32
S52	0	S51 and relative velocity and relative position and motion attribute discriminating	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/13 11:32
S53	6196	((356/28.5,27,28,4.09-4.1) or (701/93-98,116-119,301,302,28)).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/09/15 13:21
S54	0	S53 and relitave postion and relitave velocity and motion attribute discriminat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S55	0	S53 and relitave postion and relitave velocity and motion attribute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S56	0	S53 and relitave postion and relitave velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21

EAST Search History

S57	1	S53 and relative position and relative velocity and motion attribute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S58	2320	Takahama.inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S59	43	S58 and relative position	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S60	4	S59 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S61	8	S58 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S62	125	S58 and (laser radar or laser or radar)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S63	27	S62 and vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S64	163	S53 and relative position and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21

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S65	137	S64 and (radar or laser)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S66	0	S64 and relative position same calculat\$3 near4 multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S67	0	S64 and relative position same calculat\$3 same multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S68	50	S64 and relative position same calculat\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S69	0	S64 and calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S70	176	calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S71	28	calculat\$3 near3 multiple near7 accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S72	36	S65 and stationary object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21

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S73	41	S65 and (immobile or still or stationary or motionless) object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S74	19	S65 and (immobile or still or stationary or motionless) object same vehicle same relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S75	0	S65 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat@4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S76	9	S65 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S77	8970	((701/93,96,301,302) or (340/425.5, 435,436,438,901,903) or (342/61, 70)).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/09/15 13:21
S78	0	S77 and relative velocity and relative position and motion attribute discriminating	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S79	6196	((356/28.5,27,28,4.09-4.1) or (701/93-98,116-119,301,302,28)).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/09/15 13:21
S80	163	S79 and relative position and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21

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S81	137	S80 and (radar or laser)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S82	19	S81 and (immobile or still or stationary or motionless) object same vehicle same relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S83	0	S80 and relative position same calculat\$3 same multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S84	0	S80 and relative position same calculat\$3 near4 multiple	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S85	0	S79 and relitave postion and relitave velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S86	0	S80 and calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S87	2320	Takahama.inv.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S88	0	S79 and relitave postion and relitave velocity and motion attibute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21

EAST Search History

S89	43	S87 and relative position	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S90	4	S89 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S91	8	S87 and relative velocity	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S92	0	S79 and relitave postion and relitave velocity and motion attribute discriminat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S93	176	calculat\$3 near3 multiple same accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S94	8970	((701/93,96,301,302) or (340/425.5, 435,436,438,901,903) or (342/61, 70)).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/09/15 13:21
S95	0	S94 and relative velocity and relative position and motion attribute discriminating	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S96	125	S87 and (laser radar or laser or radar)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21

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S97	1	S79 and relative position and relative velocity and motion attribute	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S98	9	S81 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S99	36	S81 and stationary object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S100	28	calculat\$3 near3 multiple near7 accuracy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S101	50	S80 and relative position same calculat\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S102	27	S96 and vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S103	0	S81 and (immobile or still or stationary or motionless) object same vehicle same relative velocity same calculat@4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21
S104	41	S81 and (immobile or still or stationary or motionless) object same vehicle	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	NEAR	ON	2006/09/15 13:21

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	0	relative position detecting and relative velocity calculating and vehicle velocity detection and motion attribute discriminating and relative velocity and candidate and plurality of relative velocity	US-PGPUB	NEAR	ON	2007/01/16 13:13
L2	0	relative position detecting and relative velocity calculating and vehicle velocity detection and motion attribute discriminating and relative velocity and candidate and plurality of relative velocity.clm.	US-PGPUB	NEAR	ON	2007/01/16 13:13
L3	0	relative position detecting and relative velocity calculating and vehicle velocity detection and motion attribute discriminating and relative velocity and candidate and plurality.clm.	US-PGPUB	NEAR	ON	2007/01/16 13:13
L4	0	relative position detecting and relative velocity calculating and vehicle velocity detection and motion attribute discriminating and relative velocity and candidate.clm.	US-PGPUB	NEAR	ON	2007/01/16 13:14
L5	0	relative position detecting and relative velocity calculating and vehicle velocity detection and motion attribute discriminating and relative velocity.clm.	US-PGPUB	NEAR	ON	2007/01/16 13:14
L6	0	relative position detecting and relative velocity calculating and vehicle velocity detection and motion attribute discriminating and relative.clm.	US-PGPUB	NEAR	ON	2007/01/16 13:14
L7	0	relative position detecting and relative velocity calculating and vehicle velocity detection and motion attribute discriminating.clm.	US-PGPUB	NEAR	ON	2007/01/16 13:14
L8	0	relative position detecting and relative velocity calculating and vehicle velocity detection and motion attribute.clm.	US-PGPUB	NEAR	ON	2007/01/16 13:14
L9	0	relative position detecting and relative velocity calculating and vehicle velocity detection and motion.clm.	US-PGPUB	NEAR	ON	2007/01/16 13:14
L10	0	relative position detecting and relative velocity calculating and vehicle velocity detection.clm.	US-PGPUB	NEAR	ON	2007/01/16 13:14

EAST Search History

L11	1	relative position detecting and relative velocity calculating and vehicle.clm.	US-PGPUB	NEAR	ON	2007/01/16 13:14
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